McErlang – a Model Checker for Erlang Programs

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McErlang basics

- McErlang is useful for checking *concurrent software*, not for checking sequential software.

- The Erlang runtime system for processes & communication is replaced with a new runtime system written in Erlang (erlang:send, spawn, ... have been reimplemented).

- A concurrent program is checked under all possible schedulings.

- McErlang is open source, available under a BSD license.
The McErlang model checker: Design Goals

- Reduce the gap between program and verifiable model (the program is the model)
- Write correctness properties in Erlang
- Implement verification methods that permit partial model checking when state spaces are too big (Holzmann’s bitspace algorithms)
- Implement the model checker in a parametric fashion (easy to plug-in new algorithms, new abstractions, . . .)
Two processes are spawned, the first starts an “echo” server that echoes received messages, and the second invokes the echo server:

```
-module(example).
-export([start/0]).

start() ->
    spawn(fun() ->
        register(echo,self()),
        echo()
    end),
    spawn(fun() ->
        echo!{msg,self(),'hello world'},
        receive
            {echo,Msg} -> Msg
        end
    end).

echo() ->
    receive
        {msg,Client,Msg} ->
            Client!{echo,Msg}, echo()
    end.
```
Example under normal Erlang

Let’s run the example under the standard Erlang runtime system:

```erlang
> erlc example.erl
> erl
Erlang R13B02 (erts-5.7.3) ...

1> example:start().
<0.34.0>
2>
```

That worked fine. Let’s try it under McErlang instead.
Example under McErlang

First have to recompile the module using the McErlang compiler:

> mcerl_compiler -sources example.erl
Example under McErlang

First have to recompile the module using the McErlang compiler:

> mcerl_compiler -sources example.erl

Then we run it:

> erl
Erlang R13B02 (erts-5.7.3) ... 

1> example:start().
** exception error: undefined function mcerlang:spawn/1
  in function  example:start/0

Hmm... we better include the McErlang libraries and start McErlang
Example under McErlang

Lets run it with McErlang libraries and from within McErlang:

```erlang
> mcerl
Erlang R13B02 (erts-5.7.3) ...

1> mce:apply(example,start,[]).
Starting McErlang model checker environment version 1.0 ...

*** User code generated error
exception error due to reason badarg
Stack trace:
  mcerlang:resolvePid/2
  mcerlang:mce_send/2
  -example:start/0-anonymous-1-/0
...```
Investigating the Error

An error! Let’s find out more using the McErlang debugger:

2> mce_erl_debugger:start(mce:result()).
Starting debugger with a stack trace; execution terminated
user program raised an uncaught exception.

stack(@2)> showExecution().
0: process <node,1>:
    run function example:start([])
    spawn(#Fun<example.1.118053186>,[],[]) --> <node,2>
    spawn(#Fun<example.2.76847815>,[],[]) --> <node,3>
process <node,1> was terminated
process <node,1> died due to reason normal

1: process <node,3>:
    run #Fun<example.2.76847815>([])
process <node,3> died due to reason badarg
Error Cause

- Apparently in one program run the second process spawned (the one calling the echo server) was run before the echo server itself:
  
  ```
  run #Fun<example.2.76847815>(([]))
  ```

- Then upon trying to send a message

  ```
  echo!{msg,self(),'hello world'}
  ```

  the `echo` name was obviously not registered, so the program crashed
Presentation Outline

■ What is model checking & a brief comparison with testing
■ McErlang basics
■ McErlang in practise: installing and usage
■ Working with a larger example: a lift control system
What is Model Checking

- Run the program in a controlled manner so that all program states are visited (visualised as a finite state transition graph):

  ![Finite State Transition Graph]

- A node represents a **program state** which records the state of all Erlang processes, all nodes, messages in transit...

- **Graph edges** represent computation steps from one program state to another

- **Correctness Properties** are automata that run in lock-step with the program; they inspect each program state to determine whether the state is ok or not
Comparison with Random Testing

The State Space of a small program:
Testing, run 1:

Random testing explores one path through the program:
Testing, run 2:

With repeated tests the coverage improves:
Testing, run n:

But even after a lot of testing some program states may not have been visited:
Model checking: 100% coverage

Model checking can guarantee that all states are visited, without revisiting states.
What is the trick? How can we achieve 100% coverage

- Needed: the capability to take a **snapshot** of the Erlang system

  - A **program state** is: the contents of all process mailboxes, the state of all running processes, messages in transit (the ether), all nodes, monitors, ...
What is the trick? How can we achieve 100% coverage

- Needed: the capability to take a **snapshot** of the Erlang system

  - A **program state** is: the contents of all process mailboxes, the state of all running processes, messages in transit (the ether), all nodes, monitors, …

- Save the snapshot to memory and forget about it for a while

- Later continue the execution from the snapshot
Fundamental Difficulties of Model Checking

- Too many states (not enough memory to save all snapshots)
- Checking all states takes too much time
- We have to a snapshot of things outside of Erlang (hard drives due to disk writes and reads, . . . )
The McErlang approach to model checking

- The lazy solution: just execute the Erlang program to verify in the normal Erlang interpreter
- And extract the system state (processes, queues, function contexts) from the Erlang runtime system
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- The lazy solution: just execute the Erlang program to verify in the normal Erlang interpreter
- And extract the system state (processes, queues, function contexts) from the Erlang runtime system
- Too messy! We have developed a new runtime system for the process part, and still use the old runtime system to execute code with no side effects
Adapting code for the new runtime environment

Erlang code must be “compiled” by the McErlang “compiler” to run under the new runtime system:

- API changes: call `mcerlang:spawn` instead of `erlang:spawn`
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- **API changes:** call `mcerlang:spawn` instead of `erlang:spawn`

- Instead of executing (which would block)
  ```erl
  receive
    {request, ClientId} -> ...
  end
  ```
  an adapted function returns a special Erlang value describing the receive request:
  ```erl
  {'_recv_', {Fun, VarList}}
  ```

- McErlang translator works on HiPE Core Erlang code
Full Erlang Supported?

- Virtually the full core language supported:
  - Processes, nodes, links, all data types
  - Higher-order functions

Many libraries at least partly supported:

- supervisor, gen_server, gen_fsm, ets
- **Not supported:** gen_tcp, …
Full Erlang supported?

No real-time model checking implementation yet

receive
  after 20 -> ...
end

behaves the same as

receive
  after 20000 -> ...
end
Non-determinacy:

```erlang
mce_erl:choice
([fun () -> Pid!hi end,
fun () -> Pid!hola end]).
```

sends either `hi` or `hola` to `Pid` but not both
Extensions to Erlang in McErlang

- Non-determinacy:

  ```erlang
  mce_erl:choice
  ([fun () -> Pid!hi end,
    fun () -> Pid!hola end]).
  ```

  sends either hi or hola to Pid but not both

- Convenience:

  ```erlang
  mcerlang:spawn
  (new_node,
    fun () -> Pid!hello_world end)
  ```

  The node new_node is created if it does not exist
Compiling/preparing code for running under McErlang

- All source code modules of a project must be provided to the McErlang compiler

- Some OTP behaviours/libraries are automatically included at compile time

- Example: `mcerl_compile -sources *.erl`

- The translation is controlled by the `funinfo.txt` file (can be customised)

- The result of the translation is a set of `beam` files (and Core Erlang code for the translated modules)
Controlling Translation

- The file `funinfo.txt` controls the remapping of functions and describes side effects:

  ```
  [
    {gen_server, [{translated_to, mce_erl_gen_server}]},
    {supervisor, [{translated_to, mce_erl_supervisor}]},
    {gen_fsm, [{translated_to, mce_erl_gen_fsm}]},
    {erlang, [{rcv, false}]},
    {{erlang, spawn, 4},
     [rcv,
      {translated_to, {mcerlang, spawn}}]},
    {{erlang, send, 2}, [{translated_to, {mcerlang, send}}]}
    ...
  ]
  ```

- A verification project can use its own `funinfo.txt`
Choice of Libraries

- McErlang has tailored versions of some libraries: supervisor, gen_server, gen_fsm, gen_event, lists, ets, ... which are automatically included.

- It may be possible to use the standard OTP libraries instead.
Starting McErlang:

```erlang
mce:start(#mce_opts{program={Module, Fun, Args},
algorithm={Module, InitArgs},
monitor={Module, InitArgs})
```

Example: starting the Echo program

```erlang
mce:start(#mce_opts{program={example,start,[]},
algorithm={mce_alg_safety,void},
monitor={mce_mon_test,void})
```

The result of a model checking run can be retrieved using

```erlang
mce:result()
```
(a program trace leading to the bug)
McErlang runtime options

More `mce_opts()` record options:

- `sim_external_world = true() | false()`
  McErlang does I/O with external world? (false)

- `shortest = true() | false()`
  Compute the shortest path to failure? (false)

- `fail_on_exit = true() | false()`
  Stop a model checking run if a process terminates abnormally due to an uncaught exception (true)

- `time_limit = seconds`
  Halts verification after reaching a time limit

- And many more …
Algorithms

An algorithm determines the particular state space exploration strategy used by McErlang:

- **mce_alg_simulation**
  Implements a basic simulation algorithm – following a single execution path

- **mce_alg_safety**
  Checks the specified monitor on *all* program states

- **mce_alg_combine**
  Combines simulation and model checking to reduce state space
Ok, we can run programs under the McErlang runtime system. Next we need a language for expressing correctness properties:
What to check: Correctness Properties

Ok, we can run programs under the McErlang runtime system. Next we need a language for expressing correctness properties:

- We pick Erlang of course!

  A *safety monitor* is an user function with three arguments:

  ```erlang
  stateChange(State, MonitorState, Action) ->
  ...
  {ok, NewMonitorState}.
  ```
Ok, we can run programs under the McErlang runtime system. Next we need a language for expressing correctness properties:

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  A *safety monitor* is an user function with three arguments:
  
  ```erl
  stateChange(State, MonitorState, Action) ->
  ...{ok, NewMonitorState}.
  ```

- A program is checked by running it in lock-step with a monitor

- The monitor can inspect the current state, and the side effects (actions) in the last computation step

- The monitor either returns a new monitor state `{ok, NewMonitorState}`, or signals an error
Safety Monitors

- Safety Monitors check that *nothing bad ever happens*

- They must be checked in *all* the states of the program:
A monitor example

- We want to implement a monitor to check that a program alternates between sending `request` and `release`.

- As an automaton:
A monitor example implemented in Erlang

-module(req_rel_alternate).
-export([init/1,stateChange/3,monitorType/0]).
-behaviour(mce_behav_monitor).

monitorType() -> safety.
init(_) -> {ok,request}.

stateChange(ProgramState,request,Action) ->
  case get_action(Action) of
    {ok,request} -> {ok,release};
    {ok,release} -> not_alternating
    _ -> {ok,request}
  end; ...

get_action(Action) ->
  case mce_erl_actions:is_send(Action) of
    true -> {ok,mce_erl_actions:get_send_msg(Action)};
    false -> no_action
  end.
What can monitors observe?

- Program **actions** such as sending or receiving a message
- Program **state** such as the contents of process mailboxes, names of registered processes
- The values of some program variables (can be tricky)
- Programs can be instrumented with special *probe actions* that are easy to detect in monitors (e.g. calling `mce_erl:probe(requesting)`) 
- Programs can be instrumented with special *probe states*, which are *persistent* (actions are transient) (e.g. calling `mce_erl:probe_state(have_requested)`)
Some Predefined Monitors

- **mce_mon_deadlock**
  Checks that there is at least one non-deadlocked process

- **mce_mon_queue**
  Checks that all queues contain at most MaxQueueSize elements.
For expressing that *something good eventually happens*

Linear Temporal Logic (always, eventually, until, next, ...) is used to express liveness properties

State predicates are Erlang functions

Example:

```erlang
always(fun liftprop:go_to_floor/3 =>
    eventually fun liftprop:stopped_at_floor/3)
```

State predicate:

```erlang
go_to_floor(_ProgramState,Action,_PrivateData) ->
    case interpret_action(Action) of
        {f_button,Floor} -> {true,Floor};
        {e_button,_,Floor} -> {true,Floor};
        _ -> false
    end.
```
The McErlang Debugger

- There is a rudimentary debugger for examining counterexamples.

- After a failed model checking run, start the debugger on the counterexample using:
  
mce_erl_debugger:start(mce:result()).
Things that can go wrong

- McErlang runs out of memory – too many states
- McErlang takes too long
  - Why? Program uses timers, counters, random values, ... or is simply too complex
What can be done

*Partial verification – explore part of the state space*
What can be done

Partial verification – explore part of the state space

- Use a (lossy) bounded size state table:
  ```
  #mce_opts
  { ..., table={mce_table_bitHash, Size}, ... }
  ```

- Use a bounded stack
  ```
  #mce_opts
  { ..., stack={mce_stack_bounded, Size}, ... }
  ```

- Put a bound on the verification time

- Check smaller examples (a set of test cases)
Recent Developments: QuickCheck/McErlang integrated

- Write state machine specifications in QuickCheck
- Check them using `eqc_statem:commands` or `eqc_statem:parallel_commands`
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- Use normal Erlang scheduler to check programs under the *normal* Erlang scheduler
- Use Pulse to check program under a more random scheduler
- Use McErlang to check program under all schedulings
- McErlang interface will likely be distributed with the next QuickCheck release
McErlang in Practise: downloading

- [ ] https://babel.ls.fi.upm.es/trac/McErlang/

- Use subversion to check out the McErlang sources:
  
  ```
  svn checkout \\
  https://babel.ls.fi.upm.es/svn/McErlang/trunk \\
  McErlang
  ```

- Get bug fixes and improvements using subversion:
  
  ```
  svn update
  ```
Installing

- We use Ubuntu – McErlang doesn’t work well under Windows
- Compile McErlang:
  ```bash
  cd McErlang; make
  ```
- Put `scripts` directory on the command path (in Bash):
  ```bash
  export PATH=~/McErlang/scripts:$PATH
  ```
- Read the manuals:
  ```bash
  acroread doc/tutorial/tutorial.pdf
  ```
McErlang in practise: The Elevator Example

- We study the control software for a set of elevators

- Used to be part of an Erlang/OTP training course from Ericsson
The Elevator Example

Example complexity:

- **Static complexity**: around 1670 lines of code

- **Dynamic complexity**: around 10 processes (for two elevators)

- **Uses quite a few libraries**: lists, gen_event, gen_fsm, supervisor, timer, gs, application
Running the elevator under McErlang

- First we just try to run it under the McErlang runtime system (forgetting about model checking for a while)
- This will test the system under a less deterministic scheduler than the normal Erlang scheduler
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- Executing:

```erlang
mce:start
(#mce_opts
 {program={sim_sup,start_link,[1,3,2]},
  sim_external_world=true,
  algorithm={mce_alg_simulation,void}}).
```
Running the elevator under McErlang

- First we just try to run it under the McErlang runtime system (forgetting about model checking for a while)

- This will test the system under a less deterministic scheduler than the normal Erlang scheduler

- Executing:
  ```erlang
  mce:start
  (#mce_opts
   {program={sim_sup,start_link,[1,3,2]},
    sim_external_world=true,
    algorithm={mce_alg_simulation,void}}).
  ```

- Seems to work...
Model checking the elevator under McErlang

Model checking is a bit more complicated:
Model checking the elevator under McErlang

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- The \( \tau \)s graphics will not make sense when model checking \( \Rightarrow \)
  
  We shut it off in model checking mode
Model checking the elevator under McErlang

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- The $\mathcal{S}$ graphics will not make sense when model checking ⇒
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- The example is very geared to smooth graphical display ⇒
  We modify the program to only have three (3) intermediate points between elevator floors (normally 20)
Model checking is a bit more complicated:

- The graphical graphics will not make sense when model checking ⇒ We shut it off in model checking mode

- The example is very geared to smooth graphical display ⇒ We modify the program to only have three (3) intermediate points between elevator floors (normally 20)

- The program contain timers (for moving the elevator) ⇒ We assume that the program is *infinitely fast* compared to the timers: timer only release when no program action is possible
Model checking is a bit more complicated:

- The *gs* graphics will not make sense when model checking ⇒ We shut it off in model checking mode

- The example is very geared to smooth graphical display ⇒ We modify the program to only have three (3) intermediate points between elevator floors (normally 20)

- The program contain timers (for moving the elevator) ⇒ We assume that the program is *infinitely fast* compared to the timers: timer only release when no program action is possible

- In total, about 15 lines of code had to be changed to enable model checking – *not too bad!*
Scenarios

- Instead of specifying one big scenario with a really big state space, we specify a number of smaller scenarios

- Parameters:
  
  * Number of elevators,
  * Number of floors,
  * Commands:

  
  ```
  [{scheduler,f_button_pressed,[1]},
   {scheduler,e_button_pressed,[2,1]},
   {scheduler,f_button_pressed,[1]}]
  ```

- QuickCheck can be used to generate a set of scenarios
Correctness Properties

- No runtime exceptions
Correctness Properties

- No runtime exceptions

Checking:

```prolog
> mce:start(#mce_opts
   \{program={run_scenario,run_scenario,
       [2,2,[\{scheduler,f_button_pressed,[1]\}]
       algorithm={mce_alg_safety,void}\}).
```
Correctness Properties

- **No runtime exceptions**

- Checking:

  ```
  > mce:start(#mce_opts
  \{program=\{run_scenario,run_scenario,
  \[2,2,[[scheduler,f_button_pressed,[1]]]\]
  \algorithm=\{mce_alg_safety,void\}\}).
  ```

- Result:

  ```
  *** User code generated error:
  exception error due to reason \{badmatch,[]\}
  Stack trace:
  scheduler:add_to_a_stoplist near line 344/3
  scheduler:handle_cast/2
  ```
Correctness Properties

- No runtime exceptions

- Checking:

  > mce:start(#mce_opts
  {program={run_scenario,run_scenario,
    [2,2,[[scheduler,f_button_pressed,[1]]]]
  algorithm={mce_alg_safety,void}}).

- Result:

  *** User code generated error:
  exception error due to reason {badmatch,[]}
  Stack trace:
  scheduler:add_to_a_stoplist near line 344/3
  scheduler:handle_cast/2
  ...

- Bug - the system received the “press button”-command before it had been initialised
“Hiding the bug”

- Instead of fixing the bug we hide it by only sending commands when the system has started by enabling the option `is_ininitely_fast=true`

- Checking:

```
> mce:start(#mce.opts
  {program={run_scenario,run_scenario,
     [2,2,[{scheduler,f_button_pressed,[1]}]
     is_ininitely_fast=true,
     algorithm={mce_alg_safety,void}}).
```
Correctness Properties

- *An elevator only stops at a floor after receiving an order to go to that floor*

  (implemented as a monitor that keeps a set of floor requests, and checks that visited floors are in the set)
% A Monitor Implementing the Floor Request Property

-module(stop_after_order).
-behaviour(mce_behav_monitor).

%% The monitor state is a set of floor requests
init(_) -> ordsets:new().

%% Called when the program changes state
stateChange(_,FloorReqs,Action) ->
    case interpret_action(Action) of
    {f_button,Floor} ->
        ordsets:add_element(Floor,FloorReqs);
    {e_button,Elevator,Floor} ->
        ordsets:add_element(Floor,FloorReqs);
    {stopped_at,Elevator,Floor} ->
        case ordsets:is_element(Floor,FloorReqs) of
            true -> FloorReqs;
            false -> throw({bad_stop,Elevator,Floor})
        end;
    _ -> FloorReqs
    end
Checking the first correctness property

■ Checking:

```prolog
> mce:start(#mce_opts
   {program=[run_scenario,run_scenario,
             [3,2,[[scheduler,f_button_pressed,[3]]]]
   is_infinetly_fast=true,
   algorithm=[mce_alg_safety,void],
   monitor=[stop_after_order,void]}).
```

■ Fails…

■ We display the counterexample (a program trace) using a custom pretty printer:

```
Floor button 3 pressed
Elevator 1 is moving up
Elevator 1 is approaching floor 2
Elevator 1 is stopping
Elevator 1 stopped at floor 2
```
More Correctness Properties

- Refining the floor correctness property:

  An elevator only stops at a floor after receiving an order to go to that floor, if no other elevator has met the request

  (implemented as a monitor that keeps a set of floor requests; visited floors are removed from the set)
More Correctness Properties

- Refining the floor correctness property:
  
  *An elevator only stops at a floor after receiving an order to go to that floor, if no other elevator has met the request*
  
  (implemented as a monitor that keeps a set of floor requests; visited floors are removed from the set)

- A Liveness property:

  *If there is a request to go to some floor, eventually some elevator will stop there*
McErlang Status and Conclusions

- Supports a large language subset (full support for distribution and fault-tolerance and many higher-level components)
- Everything written in Erlang (programs, correctness properties, . . . )
- An alternative implementation of Erlang for testing (using a much less deterministic scheduler)
- Using McErlang and testing tools like QuickCheck can be complementary activities:
  - Use QuickCheck to generate a set of test scenarios
  - Run scenarios in McErlang
- “IDE integration” coming soon (for Emacs and Eclipse)